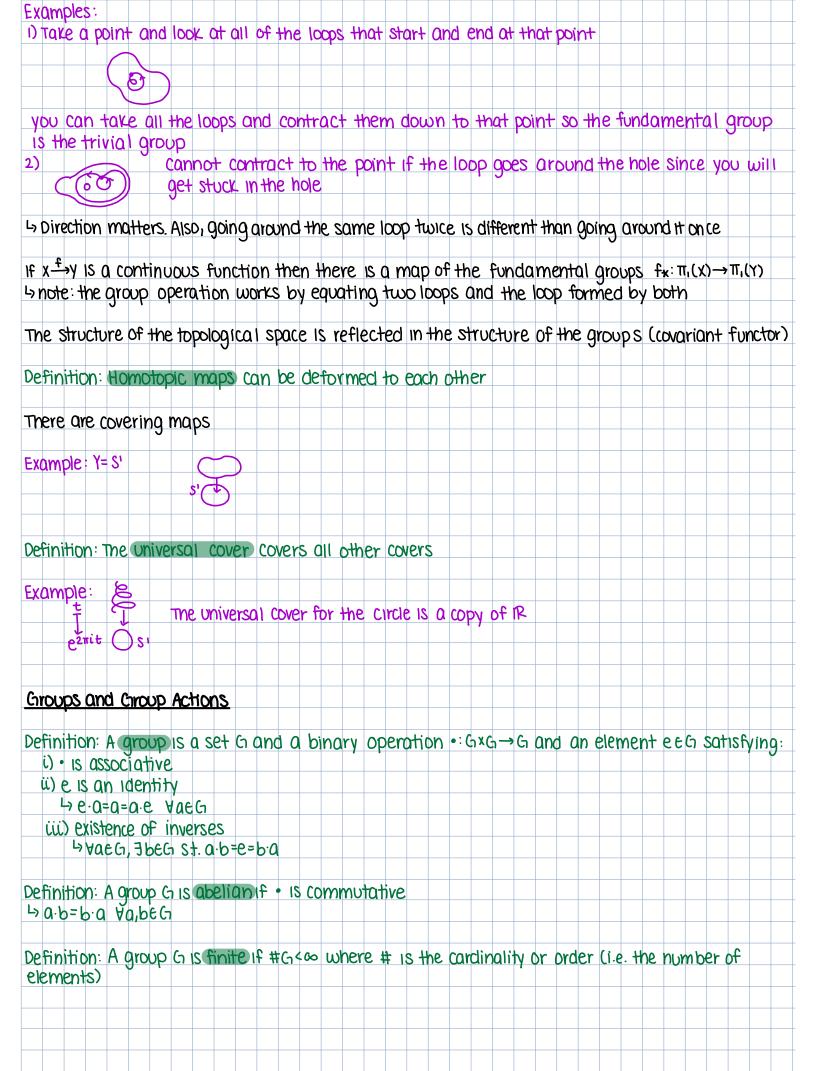
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Definition: An automorphism of the form 4(g)=h'qh, where help is fixed, is called an inner
automorphism
Example: Ca is an inner automorphism
Example: C=$3, h=(12), h=(12)
h(1)h-1=1 4h
(12)(12)(12)=(12)
                      (12)(23)(12)=(13)
                                               (12)(132)(12)=(123)
(12)(13)(12)=(23)
                      (12)(123)(12)=(132)
The inner automorphisms of an abelian group map an element to itself
Definition: A subset HSG, where G is a group, is a subgroup, denoted HSG, if (H, · | HxH, e) is
itself a group
4) Le 14 is a subset that is itself a group with respect to the same binary operation and identity
  as G
The Subgroup Test: HSG is a subgroup if and only if
 i) H = Ø
 (i) Ya, beh, abeH { 1.e. Ya, beH a.b'eH
iii) YaeH, a-1eH
4 If G is finite, you only need the first two
Example: YG, £13 < G is a subgroup denoted 1 (or 0 if G is additive)
1 is called the trivial subgroup
Similarly, G = G
is these are the only two subsets that are subgroups VG. Further, there are groups in which these
  are the only subgroups
Definition: If H=G and H=G (i.e. H is a proper subset of G) then H is a proper subgroup
5 Typically you would ask for any non-trivial proper subgroups
Examples:
 1) Aut(6) < SG
 2) The inner automorphisms of a group is denoted Inn(4)
  b claim: Inn (G) = Aut (G)
    Proof:
       i) Yaea, Caelnn(G)
       ii) let (g, Cn & Inn (G), then cg > Ch = (gn since g(nah-1)g-1= (gn) a (gn)-1
      iii) if Cae Inn (G) then Ca'= Car & Inn (G)
3) Z & R as additive groups
4) SLn(IR) & Giln(IR)
  > Definition: SLn(R)= { real nxn matrices m: det(m)=13
   Proof:
     i) det (I) = 1 € SLn(IR)
     ii) let ABE SLh(1R), then det(AB)=det(A)det(B)=1
     (ii) let Ae SLn (IR) then det (A-1)= (det A) = 1
We can also get subgroups from homomorphisms. There are two important subgroups: the image
of a homomorphism and the Kernel of a homomorphism
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Definition: If 4:G-G' is a group homomorphism, the image of 4 denoted im(4):= {4(g):ge G3
الله (ع) خ ه ا
Motivation for the kernel: Given a homomorphism 4:6→61, you get an equivalence relation on the
domain, G. For a, beG, define a~b if 4(a)=4(b). Denote the set of equivalence classes by
G/~= { (a) a ε G } where [a] = {b ε G : b ~ a }. Then \( \Pi \) induces a bijection \( \overline{\Pi} : \Gamma / \sigma \) im(\( \pi \))
(bijective from the definition of equivalence classes). The right hand side, Im (4), is a group so the
bijection induces a group structure on the left hand side, G/~.
Another description of ~:
claim: I a subgroup KEG such that a~b if and only if ak=bk (where ak= sak: kek3) if and only if
a'bek. In particular, [a]=ak. ak=bk=> ykek, ak=bk' for k'ek=> kk'-'=a'b
Definition: The Kernel of \varphi, denoted ker(\varphi), is the above k. i.e. [1]=1k=k=\varphi^{-1}(1)
Proposition: Ker (4)≤G

    Ker(Ψ)=Ψ⁻¹({e3})

More generally, if H'≤G' then 9+(H')≤G (the converse is not true)
Definition: [a]=ak is called a (left) coset of k and G/~ is denoted G/k
More generally, if H \( \) define a \( \) if and only if a \( \) b \( \) if and only if a \( \) = \( \) H.
is the equivalence classes are called left cosets and the set of them is denoted G/H
Question: For which H&G does (aH) (bH)= (a.b) H and e=1H make G/H into a group?
Abstract answer: G/H is a group if and only if H is the kernel of some homomorphism 4
□ proof:
 (<=) done previously
  (=>) if G/H is a group, define 4: G-G/H. This is by definition a homomorphism. Ker(4)=H
                                     a \mapsto aH
concrete answer: when H is normal
Definition: H \leq G is called a normal subgroup denoted, H \triangleq G, if \forall g \in H and \exists H (equivalently g H g^{-1} \in H)
where gHg-1= {ghg-1: heH}
Theorem: H is a Kernel if and only if H=G
-> proof: (exercise)
  1-> you have to show that the multiplication is well-defined i.e. consider whether aH=a'H and
    bH=b'H means abH=a'b'H making aH bH=abH is well-defined
Definition: The index of H in G is [G:H]=# G/H i.e. the number of left cosets of H
Example: G=S3, H= {1, (13)3. 15 H & G?
(12) (13) (12) 1= (23) & H => H IS not normal. Similarly any H= {1, (ij)} Is not normal. There is only one
non-trivial proper subgroup of S3. That IS, N= E1, (123), (132)3
The first isomorphism theorem: If 4: G→G' is a homomorphism then 4 induces an isomorphism
\overline{\Psi}: G/ker(\Psi) \xrightarrow{\sim} Im(\Psi)
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Example: what is GLn (IR)/SLn(IR)? Define 4: GLn(R) -> G' such that ker(4)= sln(R), then you can identify the quotient with the im(4). Use det Gln(R) → Rx (1.e. the determinant) then ker 4= SLn(R) so GLn(R)/SLn(R) = Im(det)= Rx Since if re IR + then det ((r))=r Example: Is there a non-trivial homomorphism from S₃ -> C₃? since the only non-trivial proper normal subgroup of S3 15 N= E1, (123), (132)3, we need ker (4)=N what is G/N? Is it C3? C3 has no proper non-trivial subgroups but G/N only has two elements so it cannot be C3. September 1, 2017 Chroup Actions Definition: Let G be a group and X be a set. A (left) action of G on X is a function $G \times X \longrightarrow X$ $(g, \chi) \mapsto g \circ \chi$ where $g \cdot x$ is "a acting on x" satisfying: i) 1 • x = x ∀ x ∈ X (i) \di, q2 \(\mathreag{C1}\) and \(\frac{1}{2} \in \chi) = (q1 \, q2) \cdot \chi) The set x is called a G-set. We say G acts on x, denoted GC X Examples: 1) $G=S_n$ $x=\{1,2,...,n\}$, then $\sigma \cdot x = \sigma(x)$ 2) C=Dn, X=regular n-gon Remark: For geGC X, the map $\sigma_g: X \to X$ is in Sx (the group of bijections from X to itself) 4) Proof: Claim: (og) = og-1 L> Proof: $(\sigma_q \circ \sigma_{q-1})(x) = q \circ (q^1 \circ x) = (q \cdot q^1) \circ x = 1 \circ x = x$. Similarly, $(\sigma_{q^1} \circ \sigma_{q})(x) = x \square$ The data of a group action $G \times X \longrightarrow X$ is the same as giving a nomomorphism $\varphi: G \longrightarrow S_X$ $g \mapsto \sigma_{\mathbf{q}}$ Definition: If ch is a group and x is a set, a homomorphism $G \rightarrow Sx$ is called a permutation representation of G 14 gives a concrete representation of G Example: Dn -> Sn by labelling the vertices Cayley's Theorem: Every group is a permutation group > Proof: G. G. G. by left multiplication with g.h=gh. This gives a map G→SG and multiplication by G is a bijection 🖾 Definition: An action GC x is called faithful if $G \rightarrow Sx$ is injective, we say that the map $G \rightarrow Sx$ is a faithful representation of G. The Kernel of the action is ker (GC X) = Ker (G -> SX) is since the kernel of a homomorphism is trivial if and only if the map is injective, the action GCX is faithful if the kernel is trivial

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Examples:
1) Cayley's Theorem gives us that GCG by left multiplication is faithful
2) Dn→Sn, n≥3 is faithful where Dn is acting on the n vertices of the regular n-gon.
  4 on assignment we saw this is not true for n=2
3) G=S3, X= £1,2,33 If a=(12) eG, (12) • 3=3 but (12) • 1= 2 + 1 SO GCX is faithful
Definition: ge G acts trivially on xe x if g x=x. Similarly G acts trivially on x if g x= x yge G yxex
Example: G=S3, X={1,2,33. (12) acts trivially on 3
Faithful means the only element that acts trivially on every XEX IS 16 G
Definition: If GC X, x & X. The stabilizer of x (in G) is stab G(x) = {g & G : g • x = x } i.e. the ged that acts
trivially on x (also denoted Gx). The orbit of x (under G) is Gx= Eg·x: geG3 (also denoted orb G(x))
Example: G= S3 @ [1,2,3]
                          Orbs3 (3)= {1,2,3}= X
Stabs_3(3) = \{1, (12)\}
Stabs3 (2)= {1, (13)}
                          Orbs3 (2)= X
Stab s3 (1) = {1, (23)}
                          Orb S3 (1) = X
4 This shows that elements can have stabilizers but still have the action be faithful
Proposition: Ker (GCX) = 1 Stab (X)
Proposition:
i) YXEX, StabG(x) & G (and OrbG(x) is a G-set)
  1-> In fact, orba(x) is the smallest set containing x on which a acts
ii) The orbits of the action partition X
   5 Thus any two orbits that share an element are equal
iii) If Gx=Gx' then stab G(x) and stab G(x') are conjugate (i.e. 7 ges such that gstab G(x) q'= stab G(x')
   5 since conjugation is a bijection, this means they're isomorphic
5 Proof:
   i) \forall x, 1 = Staba(x) so Staba(x) \neq \emptyset. If Q,Q' \in Staba(x) \Rightarrow (QQ') \cdot x = Q \cdot (Q' \cdot x) = Q \cdot x = x \Rightarrow QQ' \in Staba(x) so
      staba(x) is closed under multiplication. If ge staba(x), then gox=x and go(gox)=go(x+>
      (q'q) \cdot x = q' \cdot x = x = q' \cdot x \text{ so } q' \in \text{Stab}_{G}(x)
  ii) to show the equivalence classes are an equivalence relation. Define x x if I ge G such that
     x'=q·x. Our claim is that this is an equivalence relation and the equivalence classes are the
     orbits. Since the equivalence classes of any equivalence relation partition the set.
    reflexive: x=1 - x so x~x
    symmetric: if x'=g \cdot x then g' \cdot x' = x so x' \sim x if and only if x \sim x'
    transitive: If x'=g \cdot x and x''=h \cdot x' then x''=hg \cdot x so x \sim x', x' \sim x'' \Rightarrow x \sim x'' and
    [x]= {x'e X: x'~x}= {q.x: qe6}= Gx
 iii) If x'=g \cdot x and hestabe(x) then h \cdot x = x so x=g' \cdot x and hg' \cdot x'=g' \cdot x' \Rightarrow ghg' \cdot x' = x' so he stabe(x)
     If and only if angle stab a(x1)
Example: we saw for S3 C E1,2,33 there is one orbit so the stabilizers are all conjugate (i.e. isomorphic)
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Example: Tetrahedron (4 equilateral triangles) Let T (the Tetrahedral Group) be the group of rotational symmetries of the tetrahedron 1.e. T = Ege SO3(IR): g(T)=T3 where SO3(IR) is the special orthogonal group of 3×3 matrices i.e. ggT=I and det(g)=1 W, i.e. the rotations fixing the origin, o, in IR3 Question: What is T? Let $G = \Pi$, $X = \{vertices\}$. Let v be the top vertex. $Stab_{\Pi}(v) = \{1, \rho, \rho^2, ...\}$ where p is rotation clockwise by 120° so #Stab (v) > 3. Orb_(v)=x => #Orb_(v)=4. Thus by the orbit-stabilizer theorem, #1123.4=12 since we labelled the vertices we have a map φ: π -> Su (the action map) Question: Is the action faithful i.e. is 4 injective? let geT such that govieve regeker(4). Is g=I? Think of the vertices as position vectors instead of points. Let the position vector of vi be wi then q. Vi=Vi => q. Wi=Wi. Any three of these vectors form a basis of R3 1.e. W, W2, W3 form a basis => q= I since if you have a linear map that does nothing to a basis, it must be the identity => TT → Sy, #Sy = 4! = 24, and #T ≥ 12. By Lagrange's Theorem, #T = 12 or 24 Question: Does there exist an element in Sy not in T? Yes (12) € TT (first day). You would have to flip (34) => #TT=12 Since An IS the only index two subgroup Of $S_n \Rightarrow T \cong A_4$ Note: If you can take a group and map it into Sn, you can know a lot about it Example: cube The symmetry group of the cube is denoted of and is called the octanedral group since the octanedron is dual to the cube. The notion of duality comes from the idea that an object comes from three sets 6= of objects: vertices (o dimensional), edges (I dimensional), and faces (2 dimensional) if you switch the roles of the vertices and faces of the cube, you get an octahedron (The dual of a tetrahedron is itself) 0= { 9 € SO3 (IR) : 9 (6) = 63 $stabe(v) = \{1, \rho, \rho^2, ...\}, \rho = rotation by 120^\circ$ Oc vertices: Orbo(ν)= V= {vertices } => #023.8=24 Theres nothing special about vertices. You could also use the faces Ceasier way to see the stabilizer) to get 4.6=24, or edges to get 2.12=24 eight vertices => V: O→ S8 Six faces => F: O -> S6 twelve edges => E: O -> S12 would be easier to study faces since there are less of them but there's an even smaller set to study You could act on the pairs of opposite faces (3 of them) but this would give a map to sa and #0224, #53=6 which wouldn't help much. Instead, consider x= { pairs of opposite vertices}, #x=4 so 4:0→ S4 thus if 4 is injective, then O 2 S4.

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Then x= {{wi,-wi33}
If a. Ewi-wiz= Ewj,-wi3 Vi=1,2,3,4 +nen is a= I?
consider w, w2, w3. If $ i=1,2,3 s.t. g · wi=wi then w40G q · w2=-w2 so
                  0
By definition deta=1=> wloch g.w.=w., q.w3=-w3
Now look at wi, wz, wy to get detg=1=> g · wy= - wy but looking at wz, wz, wy, detg=-1+1-
50 q · W · = W · ∀ · => q = I => 6 ≥ Sy
class Equations
Let G be a group and X=G, then GCG by q·a=gag-1 (left action)
Definition: A right action of G on X, denoted x \supset G is a function x \times G \longrightarrow x satisfying:
i) x'= x Yxex
(i) (x9)^h = x9^h \forall x \in X, \forall q, h \in C_1
Thus G5G by a9:= g-'ag since (a)9h=(gh)-'a(gh)=h-'g'agh=(g-'ag)h=(a9)h
is note: If you have a group and you see this exponent notation, it means conjugation
Definition: An orbit of the above action is called conjugacy class i.e. the conjugacy class of a
is logagige G3
-> conjugacy class of 1 is 1
→ the conjugacy class of zez(G) is {z}
-> note: the conjugacy class of a contains 1-1 a 1 = {a3
→ can never contain everything (1 is in its own class)
Definition: The stabilizer of the action, staba (a) = {gea: gag=a3={gea: ag=ga3 is the centralizer.
The kernel is fgeg: gag= a taegs= fgeg: ag=ga vaegy=z(g) - the center (notation used previously)
If x=G=Uorbits, note: #orba(g)=1 iff geZ(g)
Theorem (Class Equation): If G is a finite group and g.,.., greG be a set of representatives of the
conjugacy classes that arent in zca), then #G=#Z(G)+ = [G:Ca(gi)]
>note: #Z(G) and [G: CG(Gi)] divide #G
4> Proof: #G= Z#orbits. If #orbg(g)=1 => ge Z(G) so collect the orbits of size one otherwise,
  #0rb(9)= #G #Stab(9i)
                         but Staba(gi)= Ca(gi) and #6 = [GiH] by definition so
  [G: Ca(gi)]= #Orba(gi)
```

September 8,2015
vanala: Summadrias at the ism solo advana
xample symmetries of the icosahedron
et I=icosahedron group=rotational symmetries in IR3 of the icosahedron=rotational symmetries
f the dodecahedron= rotational symmetries of the dodecahedron (since they are dual)
ne dodecahedron consists of 12 faces that are regular 5-gons, 30 edges, and 20 vertices.
cosahedron is 20 equilateral triangles (note: this example is covered in section 6.2 of Artin's
lgebra)
westion: For which n do we have a helpful map $I \rightarrow S_n$?
rick: There are five cubes inscribed inside a dodecahedron and I permutes the cubes
iving a map φ : I→S ₅ .
ouestion: what is #I?
le can use the orbit-stabilizer theorem
ct on the 12 faces: the stabilizer of a face is 5 rotations and the orbit is all 12 faces
> #I=5·12=60.
we show the map is injective the it's as we do this by showing that £13 and I are the only
formal subgroups of I, thus any map from I to another group 15 either injective or the trivial
nap.
→ (Theorem: The class equation of I is 60=1+15+20+12+12)
-> Claim: There are no proper nontrivial subgroups
> proof: A normal subgroup is a union of conjugacy classes and contains {13. Thus if N=I
then #N=1+(sum of numbers from £15,20,12,123) s.t. #N/60. This is impossible unless
#N+1,60 D
nerefore ker(4)=1, I. However, any nontrivial rotation of a face gives a nontrivial permutation
f the cubes ⇒ Ker4≠I. Thus Ker4=1=>I ← \$5 and 4(I) has index 2 ⇒ 4:I ← As
Un Cast VIA unas Usono and un Institutio I organia populari di cultura una
of the fact, and not not not not not the first of the subject of t
In fact, ∀An, n≥5, there are no nontrivial proper normal subgroups
lass equation: You can partition elements by their order. $\forall \sigma \in G$, $\# \sigma = \# \sigma^9 \ \forall g \in G$

Proof of Previous Theorem: Break up I into elements of a given order:	
order 1: {1}	
order 2: Let e be an edge. The stabilizer of an edge consists of the identity	and the element
that rotates around the center of the edge.	
opposite edges have the same stabilizer so we have 30/2=15 elements of order	2.
order 3: let v be a vertex. For each vertex there are two nontrivial elements an	
vertices have the same stabilizer so we get $\frac{20.2}{2} = 20$ elements of order 3	
order 5: let f be a face. we've said the stabilizer has order 5 and opposite fac	es have the same
stabilizer so 12.4/2 = 24 elements	
Question: Are there others?	
No, since 60=1+15+20+24	
Claim: All elements of order 2 are conjugate	
5 proof The edges form an orbit so the stabilizer of any two elements, s	table) and stable)
are conjugate. Since 1 is conjugate to 1 => stable = [1, pe] and stable >= [1,	Only Hoop of is
	pers, men pers
conjugate to per 🗸	
claim: All elements of order 3 are conjugate	
→ proof: Again, stab (v) and stab (v') are conjugate.	
Let $stab(v)=\{1, \rho v, \rho v^{-1}\}$ and $stab(v')=\{1, \rho v', \rho v'^{-1}\}$ where ρv is a clockwise r	otation and so is
$\rho_{v'}$ if \overline{v} is the opposite vertex then $\operatorname{Stab}(\overline{v}) = \operatorname{Stab}(v)$ and $\rho_{\overline{v}} = \rho_{\overline{v'}}$, $\rho_{v} = \rho_{\overline{v'}}$.	Also pu is
conjugate to $p_{\overline{v}}$ by the rotation bringing v to \overline{v}	
Now for any two faces, f and f!, stab(f)=stab(f') but the elements break	up into two
con v acies.	
consider two opposite faces, f and F, then pf = px-1 and pf is conjugate to px	for the same
reason as with vertices. Thus #[pf] ≥ 12 and if pf is conjugate to pf2 (pf ^	Pe2) then
#[pf]=24 but #[pf] 60 so pf > pf 2, thus 24 breaks up into 24 = 12 + 12 12	
#[pf]=24 but #[pf] 60 so pt ~ pt 2, thus 24 breaks up into 24=12+12 12	
#[pf]=24 but #[pf] 60 so pt pp pf2, thus 24 breaks up into 24 = 12 + 12 12 12 Definition: A group G is called simple if G = {1} and its only normal subgro	
Definition: A group G is called simple if G = {1} and i+s only normal subgro	
Definition: A group G is called simple if G= {1} and i+s only normal subgroitself.	
Definition: A group G is called simple if G = {1} and its only normal subgroitself.	oups are £13 and
Definition: A group G is called simple if G = {1} and its only normal subgro itself. Examples: 1) If p is prime, Cp is simple since the only divisors are p and 1. Further, i	oups are £13 and
Definition: A group G is called simple if G = {1} and i+s only normal subgroitself. Examples: 1) If p is prime, Cp is simple since the only divisors are p and 1 Further, i abelian simple group, then G \(\colon	oups are £13 and
Definition: A group G is called simple if G = {1} and its only normal subgroitself. Examples: 1) If p is prime, Cp is simple since the only divisors are p and 1. Further, if abelian simple group, then G \cong Cp 2) I \cong As is the smallest non-abelian simple group	oups are £13 and
Definition: A group G is called simple if G = {1} and its only normal subgroitself. Examples: 1) If p is prime, Cp is simple since the only divisors are p and 1. Further, is abelian simple group, then G \cong Cp 2) I \cong As is the smallest non-abelian simple group 3) The next smallest has order 162. It is GL3 (IF2) = PSL2 (IF7)	oups are £13 and
Definition: A group G is called simple if G = {1} and its only normal subgroitself. Examples: 1) If p is prime, Cp is simple since the only divisors are p and 1. Further, if abelian simple group, then G \cong Cp 2) I \cong As is the smallest non-abelian simple group	oups are £13 and
Definition: A group G is called simple if $G \neq \{1\}$ and its only normal subgroitself. Examples: 1) If p is prime, G is simple since the only divisors are p and 1. Further, in abelian simple group, then $G \cong G$ p 2) G is the smallest non-abelian simple group 3) The next smallest has order G is G is G is G is G is G and G is G in G is G is G is G in G is G in G	oups are £13 and If G 18 a finite
Definition: A group G is called simple if G = {1} and its only normal subgroitself. Examples: 1) If p is prime, Cp is simple since the only divisors are p and 1. Further, is abelian simple group, then G \(\text{Cp} \) 2) I \(\text{As} \) is the smallest non-abelian simple group 3) The next smallest has order 162. It is GL3 (IF2) = PSL2 (IF7) 4) An for n \(\text{2} \) and n \(\text{4} \) is simple Tordan-Holder Theorem: Every finite group has an "essentially unique composition."	tion series" i.e.
Definition: A group G is called simple if G \divisors and its only normal subgroitself. Examples: 1) If p is prime, Cp is simple since the only divisors are p and 1. Further, is abelian simple group, then G \cong Cp 2) I \cong As is the smallest non-abelian simple group 3) The next smallest has order 162. It is GL3 (IF2) = PSL2 (IF7) 4) An for n \cong 3 and n \div 4 is simple Tordan-Holder Theorem: Every finite group has an "essentially unique composition of the property of the prope	tion series" i.e.
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Definition: A group G is called simple if G \(\frac{1}{2} \) and its only normal subgroitself. Examples: 1) If p is prime, Cp is simple since the only divisors are p and 1. Further, is abelian simple group, then G \(\sigma \)Cp 2) I \(\sigma \) As is the smallest non-abelian simple group 3) The next smallest has order 162. It is GL3 (IF2) = PSL2 (IF7) 4) An for \(n \geq 3 \) and \(n \neq 4 \) is simple Tordan-Holder Theorem: Every finite group has an "essentially unique composition of the sequence of the seque	tion series" i.e. a composition l=k and the
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Examples:
 1) 14 < (123) > 4 $3 so the constituents are C3 and C2.
   <(123)) is the only normal subgroup so this is the only composition series
 2) 2/62 has more than one option:
   0 4 (2) 4 C 6= Z/6Z
   0 4 (3) 4 C 6= 7/6/1
 3) 14 As Since As Is simple
 4) 14A54S3.
   In fact, for n≥ 5 we have 14An 4 Sn
 5) 14 < r<sup>2</sup>> 4 < r> 4 Du
   14(s)4(s, r2)4D4
Definition: A group is solvable if its Jordan-Holder constituents are all cyclic
Example: D4,83,C6 are solvable
September 10, 2015
Fixed Points of P Groups
Definition: Let G be a group. If GCX, a fixed point is xe X such that g·x=x yge G. The set of
fixed points is denoted XG.
Definition: Fix a prime p. A finite group G is called a p-group of #G=pr.
Example: G = C_2(p=2), C_2 = \{1, \sigma\}. Let G \subset X, X finite.
Question: what are the possible orbit sizes?
Any orbit is {x, o x} so the orbit is either size 1 or 2.
Either x= o·x => x ∈ x or x ≠ o·x => #Gx=2 so #x = #x (mod 2).
Therefore, if #X is odd there is necessarily a fixed point.
is Fixed points are elements with orbit size 1
Fixed Point Theorem: Let p be prime, G be a p-group, and G C X where X is finite. Then
\# X^G = \# X \pmod{p}
4) Proof: X is a disjoint union of the orbits and #Gx = [G: stab G (x)] #G=pr. Therefore
   #GX= { divisible by P , If x & XG
   so # x = # x 6+ p(...) ← nonsingleton orbits
          union of singleton orbits
Corollary: If G is a p-group and GCX, with X finite and pt #x, then there is always a fixed
point.
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Theorem: If G is a p-group, then Z(G) = { 13
4 Proof: Let X = G\{13 and x 5 G by conjugation.
  1-> This is valid since if G acts on a set you can remove an entire orbit and G will still act
  p/#x=p-1. Thus 3 a fixed point zexo .i.e 3 z = G, z = 1 st. 9 2 = 2 4 a = G => z a = a z
  => ze Z(G) and z = 1 0
Lagrange's Theorem: If H < G, G a group, then # H | # G
Question: Is there a converse? I.e. If dl#G, does 3H & G such that #H=d?
No.
Example: G=Ay, #Ay=12 but $ H \ Ay S.t. #H=6
Cauchy's Theorem: If p is a prime and pl #G, then 3 ge G s.t. #g=p
This is a partial converse to Lagrange
L> Proof: Let Cp € X where X= ε(g1, g2, ..., gp) ∈ Gp: g1g2...gp=13\ ε1,1,...,13 and let Cp= <σ>
   with \sigma \cdot (g_1, ..., g_p) = (g_p, g_1, g_2, ..., g_{p-1}) i.e. a right cyclic shift. To show this is an action
   we need to show apa, az. ap-1=1 as the group may not be abelian.
   Note that g_p g_1 q_2 \cdots g_{p-1} = g_p (g_1 g_2 \cdots g_p) g_p = g_p (1) g_p^{-1} = 1. Thus this is an action.
   Further, #X=#GP-1-1 because we can pick gi,..., gp-1 freely from GP-1 but then gp=(g1,...,gp+1).
   Since p #G, p #X so 3 a fixed point x & x CP. Thus x = (g1, g2, ..., gp) = o.x = (gp, g1, g2, ..., gp-1)
   Therefore x is of the form (g_1,g_1,...,g_n). Also the product is 1 so g_1 \neq 1, g_1 \neq 1 \Rightarrow 2
                                Ptimes
Theorem: Agroup of order p2 is isomorphic to Cp2 or Cp x Cp.
harefore it is necessarily abelian
b Proof: 宏(的) # {13 so # 宏(的) = p or p2.
   If # 2(G)=p2 then G= 2(G) => G is abelian.
   Otherwise Z(G)=G and #G/Z(G)=#G/#Z(G)=PI/P=P=>G/Z(G) is cyclic=> G is abelian.
   # 3ge G st. #g=p2 then G= <g> ≅ Cp2. Otherwise yg ≠ 1, #g=p.
   Let 9, = | and H, = <9,7 = <9,1 > i=1,...,p-1. Let 92 & G\H, , H2 = <92> = <92) j=1,...,p-1 so 9, i = 92
   for 150, 150-1 => HINH2 = 213 so HIH2 = 29, 192 3 = G OEC, 160-1 with
   #H,H2= #H, #H2 = p2
   The function \varphi: G \longrightarrow H_1 \times H_2

g_1^i g_2^j \longmapsto (g_1^i, g_2^j)
                                                  is well-defined and a bijection.
                                   (05 i, i 5 p-1)
   => Ψ is a homomorphism and HixH2 = CpxCp => Cn = CpxCp
Sylow Theorems
Theorem: If p is prime and pilts then THEG st. #H=pi
→ This is a partial converse to Lagrange. Cayley's Theorem is j=1.
Ly Proof: By Induction □
Definition: Let G be finite and p be prime. A p-subgroup of G is H = G s.t. # H=pi for j > 1.
If pril #G (i.e. #G=pm, ptm) then a subgroup of order pr is called a sylow p-subgroup.
The set of Sylow p-subgroups of G is denoted Sylp (G). Further np (G) := # Sylp (G) (sometimes
just denoted no)
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Sylow Theorems: Let #G=prm, p/m
(I) np(G)≥1. In fact vj st. 0≤j≤r, 3H≤G st. #H=p)
  > Proof: To show: If H≤G, #H=pi, i<r then JH', H≤H'≤G with [H':H]=p 1.e. #H'=pi+1
     Let HC G/H by h · aH = hgH. (Note: h · (1H) = 1H)
     #X = [G: H] and i<r => p/[G:H]
     REXH means X=QH S.+ hgH=QH VheH iff hgegh vh iff gingeh vh iff gilgeh gh iff gengch)
     SO XH = NG(H)/H = G/H
     # NG(H)/H = # XH = #X = [G: H] (mod p) => p| [NG(H): H]
     Note: Hang(H) so NG(H)/H is a group with pl#NG(H)/H so by cauchy's Theorem 3 H'& NG(H)/H
     S.t. #H'=p. Let H' be the inverse image of H' in NG(H) then [H': H]=p and H' & G. Induction 1
(II) All sylow p-subgroups are conjugate. In fact APE Sylp (G) and AQ & G S.t. # Q=p3 ] 3 de G S.t.
   Q ≤ q Pq-1
  4 Proof: Let P. Q & Sylp (G), P = Q and let Q @ G/p by q • (AP) = (QA)P. pt # G/p so 3 qe G s.t.
     and P=aP vaea => ageaP vaea => aeaPa-1 vale a => aeaPa-1 and since conjugation is a
     bijection so #Q|#gPg-1=> Q=qPg-1 \(\overline{Q}\)
(本) np=1 (modp). In fact, np=[G:NG(P)] for any PESylp(G) and npl m.
September 16,2015
Proof of Sylow Theorem (III): Let PESYIP(G) and Sylp(G) 5 P by conjugation. By the fixed point
theorem, n_0 = \# Syl_p(G) = \# Syl_p(G)^p \pmod{p}
claim: Sylp (G)P= {P3
L> Proof: QE Sylp (G)P Iff g'Qg=Q YgEP Iff P=NG(Q) Iff P IS a Sylow P-subgroup of NG(Q)
  Since #NG(Q)/pm, #Q=pr and NG(Q) = Q but Q is also a Sylbu p-subgroup of NG(Q) so
  3 90 € NG(Q) St. 90 Q Q = P => Q=P V
=> np=1(modp)
Now consider sylp(G) 5 G by conjugation with one orbit. Stab G($) = NG(S) 45 = G so by the
Orbit-Stabilizer Theorem np= #Sylp(G) = #OrbG(P)=[G: StabG(P)]=[G:NG(P)]
=> np m since #G=prm and since PSNG(P), #NG(P)=prm so
n_{p} = \frac{\# c_{1}}{\# N_{b}(p)} = \frac{m}{m!} so m'n_{p} = m
Theorem: If p,q are primes, p<q, q = 1 (mod p) then every group of size p2q is abelian
(so if #G=p2q then G≅ Cp2xCq ≥ Cp2q or G≥ CpxCpxCq ≥ Cpx Cpq)
L> Proof: np=1 (mod p) and np1 q => np=1 since q is prime and q ≠1 (mod p)
  Claim: ng=1
  L> Proof: ng =1 (mod q) and ng/p² so ng =1,p,p². ng ≠p since p<q so p ≠1 (mod q). If ng=p²
     then p2=1 (mod q) => q1p2-1=(p-1)(p+1) => q1p-1 or q1p+1. q1p-1 since q>p and p-1<p
     so q | p+1 but q>p => q = p+1 => q = 1 (mod p) which is a contradiction /
  By Assignment 3, if no=1 and no=1, PE Sylp (ch), QESylo (G) then YgEP, heQ, gh=hg
  #P=P2 => P= Cp2 or Cp xCp and #Q=p so Q ≥ Cp and PQ=G since #P#Q=# G and PDG=1 \( \overline{D} \)
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Semidirect Products
Motivating Example: Let R be a field (or a commutative ring with 1) and let v be an n-dimensional
R-vector so V= R", then GL(V) = GLn(R) where GL(V) = £T: V → V: Tis linear and invertible $
(so nxn invertible matrices).
An affine linear transformation of V is f: V - V s.t. f(v) = Av+b where A = Mn,n (R) b = V.
If f(v)=Av+b, q(v)=A'v+b', (fog)(v)=A(A'v+b')+b=(AA')v+(b+Ab') so f is invertible iff A
Affice = the group of invertible affine linear transformations = &f: V -> V : AE GLICE)}
where the operation is function composition and f(v) = v is the identity.
As a set, Affn(R)=GLn(R) × V= {(A,b) | A & GLn(R), b & V 3 but the group Gln(R) × V nas
operation (A,b) · (A',b') = (AA',b+b') = (AA',b+Ab') so the group is not the direct product of
the groups. Also V= { I } × V = Affn(R), V = Affn(R) so (A, b') (I, b') (A, b) = (A'A, ...) = (I, ...) & V
but Gin(R)=Gin(R) × 803 € Affn(R) ≠ Affn(R) since (A,b) (A',O) (A,b)=(A,b) (A'A, A'b)=(A'A'A,...)
but in H, xH2 both H, H2 = H, x H2
we use what is called a semi-direct product to generalize the direct product to get
   Affn(R)= VX GLn(R)
Theorem: Let Nand K be two groups and KCN (i.e. we have a homomorphism 4: K -> Aut(N))
Let G=N x k as a set and define (n, k,)·(n2,k2)=(n,(k,1n2), k,k2). This defines a group
structure on G=N*K denoted NAK (or NAKK) called the semidirect product of N and K
with respect to 9.
Furthermore #G=#k·#N. Identifying Kand KxISG, and N and IXNSG we have that K,NSG,
N=G, and Nnk=1. Lastly kon = knk1, nen
15 If the action is the trivial action, then this is just the cross product
Example: Let N be abelian and k=C2=(0). Define 4:K->Au+(N)
                                                                (if a group is abelian then
                                                  σ+→(n+→n')
inversion is an automorphism)
If N=Cm=<r> then Cm × C2 has size 2m, an element (5,1) s.t. (5,1)2=1, an element (1,1) s.t.
(1,r) = 1, and or o = o r = r - 1 so Cm x C2 2 Dm
Definition: Let N, K & G. C 1s the internal direct product of N and K If
  i) G=KN (KNN=1)
  ii) The map KN-KXN IS an Isomorphism
Definition: Let N, K & G. G is an internal semidirect product if
   i) G=KN (KNN=1)
  ii) The map kn -> Nx & k is an isomorphism where 4(k) (n) = knk-1
Theorem: If G is a group and N, K & G, then KN & K × N iff
   i) K,N4G
  ii) KNN=1
G is the internal direct product iff we also have
  iii) # K # N = # G
Example: Let n=2m, m odd (i.e. n=2 (mod 4)) and consider Dn. #Dn=2n=4m. Let N=<s, r2>
(s reflection, r rotation) and K= <rm> = {1, rm3. N \( \Darrow\) Dn since [Dn: N] = 2 and K \( \Darrow\) Dn since
K=2(Dn). N∩K=1 Since m 15 odd. N≥ Dn/2 SO #N#K=n·2=2n=#Dn SO Dn=N×K=Dn/2×C2
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Case b: K \ C4
      Let K=(x), N=(y). We know xy + yx since G is not abelian
      => xyx-=y-=> C=NxyN, where \varphi: x^i \mapsto \psi^i \Rightarrow G \cong C_3 \times C_4, called the dicyclic group of
     of order 12.
G-Sets
Definition: Let X be a (left) G-set. A subset Y = X is called G-stable (or G-invariant) if G-Y = Y (i.e.
vgeG, vyeY, goveY). A G-subset of X is YEX that is a G-set under the same action
Theorem: A subset Y & X is a G-subset if and only if Y is G-stable. ("closure under action")
Definition: Let X,Y be two G-sets. A function f: X -> Y is called a morphism of G-sets (or a
G-map or a G-equivariant map) if ygeG Yxex, f(g·x)=g·f(x)
Definition: The set of G-maps X \rightarrow Y is denoted Maps(X,Y). f \in Maps(X,Y) is called an isomorphism
of G-sets if 3 femaps (X,Y) such that fof = idx and fof = idx
Theorem: feMap G(X,Y) is an isomorphism if and only if f is a bijection.
Construction: If I is a set and Xi is a G-set Vie I, then X= L Xi is a G-set
4 Note: If fi: Xi→Xi' is an isomorphism viel then f: X→X'= L Xi' is an isomorphism where
   f(x) = fi(xi) if x = xi \in Xi
Proposition: Let X be a G-set
   i) Y = x is a G-subset if and only if Y is a union of orbits
   ii) VXEX, Orba(x) = 5/staba(x) as G-sets
   \rightarrow Proof of (ii): Let H=Stab G(x) and define f: \frac{G}{H} \rightarrow Orb G(x). We showed (on 9/03)
                                                         9H \longrightarrow 9.x
      that f is a well-defined bijection.
      Let g, v & G. f(v (gH)) = f(vgH) = (vg) · x = 8 · (g · x) = 8 · (gH)
      => f is G-equivariant.
Definition: A G-set, X, is called transitive if there is only one orbit
→ If X is transitive then it is 6/H for some H
Structure Theorem for G-sets: If X is a G-set then \exists a set I and \exists i \exists G vieI such that X \cong \Box G/Hi
   > Proof: Let I= { Orba(x): x ∈ x } and let xie i (i= Orba(xi)) vieI, then X= U Orba(xi).
      Let Hi= Staba(xi) then fi: 6/Hi ~ Orba(xi) which gives f: Let G/Hi ~ Let Orba(xi)=X \(\overline{\text{Z}}\)
construction: Let x, y be G-sets and Map(x, y)=\{f: x \rightarrow y: f \text{ is a function}\}. Define GC Map(x, y)
by (a.f)(x)=g.(f(g.,x)) ("g.f=gfq"). This makes Map(x,Y) a G-set!
\rightarrow Proof: 1. f=f, (q\cdot(h\cdot f))(x)=q\cdot(h\cdot f)(q^{-1}\cdot x)=g\cdot(h\cdot f(h^{-1}\cdot (q^{-1}\cdot x))+gh\cdot f((qh)^{-1}\cdot x)=((qh)\cdot f)(x)
Proposition: Map (X,Y) = Map (X,Y) = fixed points
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Examples:
1) Z is an integral domain but not a field (2azz or 2a \le -2 or 2a =0, no inverses)
2) Q, R, and C are fields
3) Z/nz is a commutative ring. If n is composite, Z/nz is not an integral domain
4) 2/pz is a field for p, prime
5) Hamilton's Quaternions, H is not commutative.
H={a+bi+cj+dk:a,b,c,deR3
$i^2 = j^2 = 1k^2 = -1$, $ij = 1k$, $jk = i$, $1k = i$, $1k = i$, $1k = -i$, $ik = -j$
The norm is $N(q) = a^2 + b^2 + c^2 + d^2$, $\bar{q} = a - bi - cj - dk = N(q) = q\bar{q} = \bar{q}q$
\rightarrow Note: $N(q)=0$ if and only if $q=0$ so if $q\neq 0$, $q^{-1}=\frac{q}{N(q)} \Rightarrow H$ is a division ring
6) If de Z and d is not a square, then Q(10) is a field, it is called the quadratic field.
Q(10)= (a+b10: a,beQ3. If x=a+b10, x=a-b10, N(x)=xx=a=bd.
→ Note: N(a)=0 if and only if a=0 so for a ±0, a== a/N(a)
7) Let A be a ring. R=Mn(A) is a ring where if M ER, (a. a. a. a. a. a. a.
M= (: :), qij e A
$a_{n_1} \cdots a_{n_n}$
If M,M'ER, M+M'=(Qij+Q'ij)
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$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
M. M'=(Cij) where Cij = n aik a'kj
1111 Cacy Whate Cay 2: Air ari
- This is not necessarily commutative or a division ring
8) Let A be a commutative ring. Then A[x], i.e. the polynomials over A, form a ring
A[x]= { P(x)=0-+0 x+ +0xn: 0:6 A n 6 7 - 3 = } P(x)= 5: 0:xi: 0:6 A 0:±0 for all bit finitely many it
$A[x] = \{P(x) = a_0 + a_1x + + a_nx^n : a_i \in A, n \in \mathbb{Z}_{\geq 0}\} = \{P(x) = \sum_{i \geq 0} a_ix^i : a_i \in A, a_i \neq 0 \text{ for all but finitely many } i\}$
12 0(m) D (m) E N[m] D(m) + D (m) - \$ (n; +b;) x i
If $P(x)$, $Q(x) \in A[x]$, $P(x) + Q(x) = \sum_{i \geq 0} (a_i + b_i) x^i$ If $P(x)Q(x) = \sum_{i \geq 0} C_i x^i$ where $C_i = \sum_{k=0}^{\infty} a_k b_{i-k}$
03 0 4 1 2 2 3 4 4 5 5 5 5 6 6 7 4 7 5 5 6 7 5 6
4
9) If X is any set and A is any ring, Map (X, A) is a ring with (f+9)(x)=f(x)+g(x) and (f-9)(x)=f(x)g(x),
O(x)=0, 1(x)=1
$O(x)=0$, $I(x)=1$ Ly e.g. If $x=IR$ (or any topological space) $R=C(x,IR)=\{f: x\rightarrow IR: f \text{ is continuous}\}\$ is a ring. It is
O(x)=0, 1(x)=1
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O(x)=0, $1(x)=1$ Ly e.g. If $x=1R$ (or any topological space) $R=C(x,R)=\{f: x\rightarrow R: f \text{ is continuous}\}$ is a ring. It is commutative but not an integral domain since for example The image is a ring of the image in the image in the image is a ring. It is a ring of the image is a ring of the image is a ring. 10. Let I be an indexing set and Ri be rings VieI. Then $\prod_{i \in I} R_i$ is a ring.
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O(x)=0, 1(x)=1 b. e.g. if x=1R (or any topological space) R=C(x,R)={f:x}R:f is continuous} is a ring. It is Commutative but not an integral domain since for example

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Examples:
1) Zx = {±13
2) Fx F \ Eo3 if F is a field
3) For n \ge 2, (\frac{7}{n}z)^x = \{a \in \frac{7}{n}z : qcd(a,n) = 13. The zero divisors are the nonzero, non-units i.e. a
   such that gcd (a,n) > 1
4) For C(R,R), f(x)=x is not a unit but also not a zero-divisor. It is not a unit since f(o)=0.
   It is not a zero-divisor since f(x)q(x)=0 \Rightarrow q(x)=0 for x\neq 0 but q is continuous so
   \lim_{x \to a} q(x) = q(0) = 0 \Rightarrow q(x) = 0
Proposition: If R is a commutative ring, then R is an integral domain if and only if R
has no zero-divisors.
Proposition: A finite integral domain is a field
L> Proof: Let a €R, a # 0 and la: R→R since R is an integral domain, la is injective and since
   R is finite, la is surjective
   \Rightarrow \exists x \in \mathbb{R} such that la(x) = ax = 1 \square
Remark (Wedderburn): A finite division ring is a field.
Definition: Let R,R' be two rings. A function 4: R - R' is a ring homomorphism if:
   i) \varphi is a group homomorphism for (R,+,0) \rightarrow (R',+,0) i.e. \varphi(a+b)=\varphi(a)+\varphi(b)
   (i) \varphi(a \cdot b) = \varphi(a) \varphi(b)
   iii) 9(1)=1
   has the book doesn't require (iii)
Ψ is an isomorphism if ∃7: R! → R nomomorphism such that Ψ·7= ide and 7·9= ide
September 24,2015
Examples:
1) \mathbb{Z} \rightarrow \mathbb{Q}, \mathbb{Z} \rightarrow \mathbb{Z}/n\mathbb{Z} are homomorphisms
2) Let I be a set and Ri be rings VieI. Let R = \pi Ri. If jeI then \pi_j : R \longrightarrow Rj is a homomorphism
3) \varphi: H \hookrightarrow M_2(c) with \varphi(a+bi+cj+dk) = a(10)+b(i0)+c(0-i)+d(0i)
   is an injective homomorphism.
Definition: A subset SER is a subring, denoted SER, if (s,+, ,0,1) is a ring.
The identity of S needs to be the identity of R
Proposition: SSR is a subring if and only if Va, bes:
i) a+b € S
ii) -aes
iii) abes
iv) 1e S
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Examples:
1) Z = Q = R = C = H
a) If de Z is squarefree then Z[1d]={a+b\d:a,beZ3\eq(1d)
   e.g. Z[i] = Q(i) (d=-1). Z[i] is called the Gaussian integers. If d=-3 then Z[1-3] = Q(1-3) but
   in fact \omega = \frac{-1 \pm \sqrt{-3}}{2} \notin \mathbb{Z}[\sqrt{-3}] but \mathbb{Z}[\omega] = \{a + b\omega : a, b \in \mathbb{Z}\} \leq \mathbb{Q}(\sqrt{-3}) (note: \omega^3 = 1, \omega = e^{a\pi i/3})
   I will is called the Eisenstein integers.
    \mathbb{Z}\left[\frac{-1+i}{2}\right] = \{a+b(\frac{+1+i}{2}) \mid a,b \in \mathbb{Z}\} is not a subring of \mathbb{Q}(i).
                          0 = \begin{cases} 1 & \text{if } D = 2,3 \pmod{4} & \text{then } \mathbb{Z}[0] = \{a+b,0:a,b\in\mathbb{Z}\} \leq \mathbb{Q}(\sqrt{d}) \\ 1 & \text{if } D = 1 \pmod{4} \end{cases}
   In general, let
    → Z[O] is the maximal ring of this form
3) Let p be prime and \mathbb{Z}_{(p)} := \begin{cases} \frac{a}{b} \in \mathbb{Q} : \gcd(a,b) = 1, p \nmid b \end{cases} then \mathbb{Z}_{(p)} \leq \mathbb{Q} called the localization of
   Z at p
4) Let R=C(IR,R). Fix N>0 and let Sn= {fec(IR,IR): f(x)=0 for 1x1> N3. It can be shown that If
   f,ge Sn then f+ge Sn, fge Sn, Oe Sn and if 1_N(x) = \begin{cases} 1 & |x| \le N \text{ then } 1_N \cdot f = f = f \cdot 1_N \text{ V} \neq S_N \end{cases}
   thus Sn is a ring with identity 1n but 1n ≠ 1∈R (1 €Sn) so Sn is not a subring of R
Definition: The image of a homomorphism \varphi: \mathbb{R} \to \mathbb{R}' is im(\psi) = \{ \varphi(r) : r \in \mathbb{R} \}
Proposition: im (4) = R'
Definition: The Kernel of a homomorphism 9: R > R' is Ker 9= {re R: φ(r)=0}= 9-1(0)
→ Ker(4) ≥ (R,+, o) (as a subgroup)
Question: Is Ker(4)≤R?
Answer: No unless R'=0 since \varphi(1)=1+0 if R'+0 so 1 \notin Ker(\varphi)
Let P/ker q = left cosets of Ker q = {a+I: a e R} where I = ker q. This is an abelian group with
(a+I)+(b+I)=(a+b)+I
Question: is P/I a ring with (a+I)·(b+I)=(a·b)+I?
Answer: yes since \overline{\varphi}: \stackrel{p}{\swarrow}_{1} \longrightarrow im\varphi is a bijection so the structure on the left is the
corresponding ring structure on the right. Conversely, when is an additive subgroup ISR such
that P/I is a ring with (a+I)\cdot(b+I)=ab+I and 1=1+I?
Abstract Characterization: If and only if I=Ker \varphi for some ring homomorphism \varphi: R \longrightarrow R'
\hookrightarrow \varphi: R \longrightarrow P/I, Ker \varphi = I
Concrete Characteristic: If and only if YreR, YaeI, ra and areI i.e. "I absorbs products"
Definition: Such an IER as above is called a (two-sided) ideal of R, denoted IAR.
Proposition: Isk is an ideal if and only if
i) [ # Ø |
ii) Ya, be I, a-be I
iii) Ya E I , YrER, ar , ra E I
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Definition: If I = R, then P/I is called the quotient ring of R by I
Example: For all rings R, I={034R and R4R. {03 is called the trivial idea) and I=R is called the
unit ideal since if I=R then I=R if and only if JueR* with ueI. P{03=R and P/R=0.
Definition: An ideal IAR with ISR is a proper ideal.
Examples:
1) If R is commutative, R is a field if and only if I= {0} and I=R are the only ideals
2) the ideals of Z are exactly nZ={an: a e Z}, n=0
First Isomorphism Theorem: If \varphi: R \to R is a ring homomorphism then \varphi induces an isomorphism
\overline{\varphi}: \frac{P}{\ker \varphi} \xrightarrow{\sim} \operatorname{im} \varphi
 a+ker\varphi \mapsto \varphi(a)
Examples:
DLet R=C(R,R) and fix x & ER. Let I= { f & C(R,R): f(x) = 0} snow that I=R and determine P/I.
   Define ev_{x_0}: C(R,R) \longrightarrow R. This is a ring nomorphism and \ker(ev_{x_0})=1 so I=R and by the
    first isomorphism theorem, &= im(evx.)= R since vaeR, f(x)=aec(R,R)
2) Let R=C(IR,IR) and N>O then SNAR
3) I=Cc(R,R)=USN, where Cc(R,R) is the set of continuous functions with compact support is
   an ideal of R
4) If R is commutative and aek, then (a):=aR=Ear: reR3=R and is called the principal ideal
   generated by a
5) Let R=R[X] and I=(X^2+1). What is R/I?
   LOOK Q+ X+I \in \mathbb{R}/I, (X+I)^2+1+I=(X^2+1)+I=0+I SO (X+I)^2=-I
   Define \varphi: \mathbb{R}[x] \to \mathbb{C} then \ker \varphi = \mathbb{I} since if f(x) = (x^2 + 1)g(x) \in \mathbb{I} = 1 f(i) = (i^2 + 1)g(i) = 0
              f(x) \longmapsto f(i)
   => I = ker 4 and yg(x) = R[x], fg(x), r(x) = IR[x] such that g(x) = q(x)(x2+1)+r(x) where r(x)=0
   or deg(r(x)) < deg(q(x)). If q(i)=0, then r(i)=q(i)-q(i)(i^2+1)=0-0=0.
   If r(x) \neq 0, then r(x) = ax + b and a \cdot i + b = 0. a, b \in \mathbb{R} \Rightarrow i = \frac{-b}{a} \Rightarrow i \in \mathbb{R} which is a contradiction.
   => Ker 45 I.
   Im Ψ = C since for a+bie C, f(x)=a+bx gives Ψ(f(x))=a+bi.
   Thus by the first isomorphism theorem, P/I = C.
6) Let R = Q[x] and d be a squarefree integer. Then Q[x]/(x^2-D) \cong Q(\sqrt{d}).
September 29.2015
Proposition: If Z is a non-empty indexing set, R is a ring, and I = 2 V = Z, then DI= R
Definition: For any subset SSR, the ideal generated by S is (s) := \bigcap_{\substack{x \in \mathbb{R} \\ s \in \mathbb{I}}} \mathbb{I}^{\underline{a}} R.
If S = \{a_1, a_2, ...\} then (s) = (a_1, a_2, ...)
Example: If R is commutative and s={a3, then (s)=(a)={ra: reR3}
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For R noncommutative (s)={ = ris; ri: ne Z=0, sies, ri, ri'e R}
Examples:
D For any ring R, (0)=0 and (1)=R
2) Let R=Z, if a,a2,..., are Z then (a,..., ar)=(gcd (a,..., ar))
Bezout's Identity: Let a, be IZ where a land b are not both zero. Then gcd (a, b) is the least
positive element of the form autby, u, v & Z and all other such elements are the multiples
of gcd (a,b).
→ Proof: Use the extended Euclidean Algorithm 🛮
Example: (6,8) = \{6u + 8v : u, v \in \mathbb{Z}\} = (acd(6,8)) = (2)
Theorem: Every ideal in Z is principle.
> Proof: If I=0, then I=(0). Let I ≠ 0 and let n be the least positive element of I.
   claim: I=(n)
   > Proof: neI => rneI Vne I => (n) SI.
     VaeI, Ja, re Z such that a = 9n+r and 04r = n.
     a & I, n & I => qn & I => a-qn = r & I and since n is mimimal such that n >0 and o < r < n => r = 0
     => a e (n) => I E (n) \( \overline{D} \)
Definition: An integral domain in which every ideal is principal is called a Principal Ideal
Domain (PID)
Definition: An ideal I=R is called finitely generated if Jan,..., an ER such that I=(a1,...,an)
Example: If R = \mathbb{C}[x_1, x_2, ...], then I = (x_1, x_2, ...) is not finitely generated.
Definition: A ring R is Noetherian if every I = R is finitely generated.
Hilbert Basis Theorem: If R is Noetherian then so is R[x]
Definition: Let Iar, Jar
   I+J= {a+b:aEI, bEJ3=({a+b:aEI, bEJ3)=(IUJ)4R
   IJ=(\{ab: aeI, beJ\}) = \{\sum_{i=1}^{n} a_ib_i: a_ieI, b_jeJ, ne\mathbb{Z}_{\geq 0}\} \neq R
Proposition: Let R be a ring. VI, JeR, IJEInJ
L> Proof: If a∈ I, b∈ J => ab ∈ In J □
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Example: Let R= Z, I=(n), J=(m)
I+ J = {un+vm: u, v & Z3 = (gcd (m, n))
InJ = \{a \in \mathbb{Z} : m \mid a, n \mid a\} = (\ell cm (m, n))
4 e.g. If n=12, m=18, I+J=(6), IJ=(216), InJ=(36)
IJ=InJ if and only if mn=lcm(m,n) if and only if gcd(m,n)=1 if and only if I+J=Z
Proposition: If R is commutative, I, JeR and I+J=R, then IJ=InJ.
4) Proof: If I+J=R, JaeI, be J such that atb = 1. Let ceInJ, d=c. 1 = c(a+b) = ca+cb = ac+bc eIJ
   Since del, cej, bel 2
Definition: If R is commutative, I, J = R then I and J are called coprime if I+J=R.
Definition: Mar is a maximal ideal if its maximal within the set of proper ideals with
respect to inclusion S. I.e. if J=R and MSJ => M=J or J=R.
Example: Let R= Z. what are the maximal ideals?
(o) SI VIAR When is (n) S (m)?
when every multiple of n is a multiple of m i.e. when min. Thus maximal ideals are (p), where
p is prime.
Theorem: Every proper ideal is contained in a maximal ideal.
1-> Proof: Apply Zorn's Lemma. Let X be a non-empty partially ordered set such that every
   chain & e X has an upper bound. Then X has at least one maximal element. Let I = R, I \ R
   (SO R = 0). Let X= {J = R: I = J, J \ R = R , then X = O since I \ X .
   Let \( \) be a chain in X so \( \) = \( \) Ji: i \( \) Such that \( \) i, i \( \) Ji \( \) Ji \( \) Ji \( \) Ji.
   claim: & has an upper bound given by J U Ji
   → Proof: Clearly I$J and Ji$J
        i) 0 e J i V i => 0 e J => J = Ø
        ii) let a, be ] => 7 i, j such that a e Ji, be J; who assume Ji & Ji
           \Rightarrow a,b\in J_i \Rightarrow a-b\in J
        iii) if ae J => a e J; for some | => ra e J; S J YreR. Thus J & R.
           If J=R then I\in J=>I\in J; for some j=>J_j=R, but J_j is proper so J\neq R.
   Thus by Zorn's Lemma, JME X, ISM with M maximal.
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